

**EJERCICIO 1 (33:53)**

Para la teoría de Klein-Gordon, el operador campo en la teoría de Schrödinger es:

$$\hat{\Phi}(\vec{x}) = \int \frac{d\mathbf{k}}{2\pi} \frac{1}{\sqrt{2\omega_{\mathbf{k}}}} \left( a_{\mathbf{k}} e^{i\vec{k}\cdot\vec{x}} + a_{\mathbf{k}}^{\dagger} e^{-i\vec{k}\cdot\vec{x}} \right)$$

Calcular el operador campo, dependiendo del tiempo

$$\hat{\Phi}(t, \vec{x}) = e^{i t H} \hat{\Phi}(\vec{x}) e^{-i t H}$$

Considerar que

$$e^{xA} B e^{-xA} = B + [A, B] x + \frac{1}{2!} [A, [A, B]] x^2 + \frac{1}{3!} [A, [A, [A, B]]] x^3 + \dots$$

Vamos a calcular

$$e^{itH} a_{\mathbf{k}} e^{-itH}$$

De modo que  $it = x$ ;  $a_{\mathbf{k}} = B$  y  $H=A$  es el hamiltoniano de Klein-Gordon

$$H = \int \frac{d^3k}{(2\pi)^3} \omega_{\mathbf{k}} a_{(\vec{k})}^{\dagger} a_{(\vec{k})}$$

Con los siguientes conmutadores:

$$[H, a_{(\vec{k})}] = -\omega_{\mathbf{k}} a_{(\vec{k})}$$

$$[H, a_{(\vec{k})}^{\dagger}] = \omega_{\mathbf{k}} a_{(\vec{k})}^{\dagger}$$

$$e^{itH} a_{\mathbf{k}} e^{-itH} = a_{\mathbf{k}} + [H, a_{\mathbf{k}}] x + \frac{1}{2!} [H, [H, a_{\mathbf{k}}]] x^2 + \frac{1}{3!} [H, [H, [H, a_{\mathbf{k}}]]] x^3 + \dots$$

$$[H, [H, a_{\mathbf{k}}]] = [H, (-\omega_{\mathbf{k}} a_{\mathbf{k}})] = -\omega_{\mathbf{k}} [H, a_{\mathbf{k}}] = -\omega_{\mathbf{k}} (-\omega_{\mathbf{k}} a_{\mathbf{k}}) = \omega_{\mathbf{k}}^2 a_{\mathbf{k}}$$

$$[H, [H, [H, a_{\mathbf{k}}]]] = [H, (\omega_{\mathbf{k}}^2 a_{\mathbf{k}})] = \omega_{\mathbf{k}}^2 [H, a_{\mathbf{k}}] = \omega_{\mathbf{k}}^2 (-\omega_{\mathbf{k}} a_{\mathbf{k}}) = -\omega_{\mathbf{k}}^3 a_{\mathbf{k}}$$

$$e^{itH} a_{\mathbf{k}} e^{-itH} = a_{\mathbf{k}} - \omega_{\mathbf{k}} a_{\mathbf{k}} (it) + \frac{1}{2!} \omega_{\mathbf{k}}^2 a_{\mathbf{k}} (it)^2 - \frac{1}{3!} \omega_{\mathbf{k}}^3 a_{\mathbf{k}} (it)^3 + \dots$$

$$e^{itH} a_{\mathbf{k}} e^{-itH} = a_{\mathbf{k}} + (-1)\omega_{\mathbf{k}} a_{\mathbf{k}} (it) + (-1)^2 \frac{1}{2!} \omega_{\mathbf{k}}^2 a_{\mathbf{k}} (it)^2 + (-1)^3 \frac{1}{3!} \omega_{\mathbf{k}}^3 a_{\mathbf{k}} (it)^3 + \dots$$

$$e^{itH} a_{\mathbf{k}} e^{-itH} = a_{\mathbf{k}} \left( 1 + \omega_{\mathbf{k}} (-it) + \frac{1}{2!} \omega_{\mathbf{k}}^2 (-it)^2 + \frac{1}{3!} \omega_{\mathbf{k}}^3 (-it)^3 + \dots \right)$$

$$e^{itH} a_{\mathbf{k}} e^{-itH} = a_{\mathbf{k}} e^{-i\omega_{\mathbf{k}} t}$$

$$e^{itH} a_{\mathbf{k}}^{\dagger} e^{-itH} = a_{\mathbf{k}}^{\dagger} + [H, a_{\mathbf{k}}^{\dagger}] x + \frac{1}{2!} [H, [H, a_{\mathbf{k}}^{\dagger}]] x^2 + \frac{1}{3!} [H, [H, [H, a_{\mathbf{k}}^{\dagger}]]] x^3 + \dots$$

$$[H, [H, a_k^\dagger]] = [H, (\omega_k a_k^\dagger)] = \omega_k [H, a_k^\dagger] = \omega_k (\omega_k a_k^\dagger) = \omega_k^2 a_k^\dagger$$

$$[H, [H, [H, a_k^\dagger]]] = [H, (\omega_k^2 a_k^\dagger)] = \omega_k^2 [H, a_k^\dagger] = \omega_k^2 (\omega_k a_k^\dagger) = \omega_k^3 a_k^\dagger$$

$$e^{itH} a_k^\dagger e^{-itH} = a_k + \omega_k a_k^\dagger (it) + \frac{1}{2!} \omega_k^2 a_k^\dagger (it)^2 + \frac{1}{3!} \omega_k^3 a_k^\dagger (it)^3 + \dots$$

$$e^{itH} a_k^\dagger e^{-itH} = a_k^\dagger \left( 1 + \omega_k (it) + \frac{1}{2!} \omega_k^2 (it)^2 + \frac{1}{3!} \omega_k^3 (it)^3 + \dots \right)$$

$$e^{itH} a_k^\dagger e^{-itH} = a_k^\dagger e^{i\omega_k t}$$

También podría hacerse

$$(e^{itH} a_k e^{-itH} = a_k e^{-i\omega_k t})^\dagger$$

$$(e^{itH} a_k e^{-itH})^\dagger = (e^{-itH})^* a_k^\dagger (e^{-itH})^* = e^{itH} a_k^\dagger e^{-itH}$$

$$(a_k e^{-i\omega_k t})^\dagger = a_k^\dagger e^{i\omega_k t}$$

Llegando al mismo resultado.

$$e^{itH} \hat{\phi}(\vec{x}) e^{-itH} = e^{itH} \left( \int \frac{dk}{2\pi} \frac{1}{\sqrt{2\omega_k}} (a_k e^{i\vec{k}\cdot\vec{x}} + a_k^\dagger e^{-i\vec{k}\cdot\vec{x}}) \right) e^{-itH}$$

$$e^{itH} \hat{\phi}(\vec{x}) e^{-itH} = \int \frac{dk}{2\pi} \frac{1}{\sqrt{2\omega_k}} e^{itH} (a_k e^{i\vec{k}\cdot\vec{x}} + a_k^\dagger e^{-i\vec{k}\cdot\vec{x}}) e^{-itH}$$

$$e^{itH} \hat{\phi}(\vec{x}) e^{-itH} = \int \frac{dk}{2\pi} \frac{1}{\sqrt{2\omega_k}} \left( (e^{itH} a_k e^{-itH}) e^{i\vec{k}\cdot\vec{x}} + (e^{itH} a_k^\dagger e^{-itH}) e^{-i\vec{k}\cdot\vec{x}} \right)$$

$$e^{itH} \hat{\phi}(\vec{x}) e^{-itH} = \int \frac{dk}{2\pi} \frac{1}{\sqrt{2\omega_k}} \left( (a_k e^{-i\omega_k t}) e^{i\vec{k}\cdot\vec{x}} + (a_k^\dagger e^{i\omega_k t}) e^{-i\vec{k}\cdot\vec{x}} \right)$$

$$e^{itH} \hat{\phi}(\vec{x}) e^{-itH} = \int \frac{dk}{2\pi} \frac{1}{\sqrt{2\omega_k}} \left( a_k e^{-i\omega_k t + i\vec{k}\cdot\vec{x}} + a_k^\dagger e^{i\omega_k t - i\vec{k}\cdot\vec{x}} \right)$$

**EJERCICIOS 2 (59:05)**

El operado de evolución en la imagen de interacción es:

$$U_I(t) = e^{i t H_0} e^{-i t H}$$

**2.1 Comprobar que**

$$U_I(t, t') = e^{i t H_0} e^{-i(t-t') H} e^{-i t' H_0}$$

$$U_I(t, t') = U_I(t) U_I^\dagger(t')$$

$$U_I(t, t') = (e^{i t H_0} e^{-i t H}) (e^{i t' H_0} e^{-i t' H})^\dagger$$

$$U_I(t, t') = (e^{i t H_0} e^{-i t H}) (e^{i t' H} e^{-i t' H_0})$$

$$\boxed{U_I(t, t') = e^{i t H_0} e^{-i(t-t') H} e^{-i t' H_0}}$$

**2.2 Comprobar que  $U_I(t, t')$  es solución de**

$$i \partial_t U_I(t, t') = H' U_I(t, t')$$

$$U_I(t, t') = e^{i t H_0} e^{-i(t-t') H} e^{-i t' H_0} = e^{-i t (H-H_0)} e^{i t' (H-H_0)}$$

$$\partial_t U_I(t, t') = -i(H - H_0) e^{-i t (H-H_0)} e^{i t' (H-H_0)} = -i(H - H_0) U_I(t, t')$$

$$i \partial_t U_I(t, t') = (H - H_0) U_I(t, t')$$

Recordando que  $H' = H - H_0$

$$\boxed{i \partial_t U_I(t, t') = H' U_I(t, t')}$$

**2.3 Verificar que cumple (estos operadores conforman un grupo) para  $t_1 > t_2 > t_3$**

$$U_I(t_1, t_2) U_I(t_2, t_3) = U_I(t_1, t_3)$$

$$U_I(t_1, t_2) = e^{i t_1 H_0} e^{-i(t_1-t_2) H} e^{-i t_2 H_0}$$

$$U_I(t_2, t_3) = e^{i t_2 H_0} e^{-i(t_2-t_3) H} e^{-i t_3 H_0}$$

$$U_I(t_1, t_2) U_I(t_2, t_3) = e^{i t_1 H_0} e^{-i(t_1-t_2) H} e^{-i t_2 H_0} e^{i t_2 H_0} e^{-i(t_2-t_3) H} e^{-i t_3 H_0}$$

$$U_I(t_1, t_2) U_I(t_2, t_3) = e^{i t_1 H_0} e^{-i(t_1-t_2) H} 1 e^{-i(t_2-t_3) H} e^{-i t_3 H_0}$$

$$U_I(t_1, t_2) U_I(t_2, t_3) = e^{i t_1 H_0} e^{-i(t_1-t_2) H} e^{-i(t_2-t_3) H} e^{-i t_3 H_0}$$

$$U_I(t_1, t_2) U_I(t_2, t_3) = e^{i t_1 H_0} e^{-i(t_1-t_3) H} e^{-i t_3 H_0}$$

2.4 Demostrar que

$$U_I(t_1, t_3) U_I^\dagger(t_2, t_3) = U_I(t_1, t_2)$$

$$(U_I(t_2, t_3))^\dagger = (e^{i t_2 H_0} e^{-i(t_2-t_3)H} e^{-i t_3 H_0})^\dagger = e^{i t_3 H_0} e^{i(t_2-t_3)H} e^{-i t_2 H_0}$$

$$U_I(t_1, t_3) (U_I(t_2, t_3))^\dagger = (e^{i t_1 H_0} e^{-i(t_1-t_3)H} e^{-i t_3 H_0}) (e^{i t_3 H_0} e^{i(t_2-t_3)H} e^{-i t_2 H_0})$$

$$U_I(t_1, t_3) (U_I(t_2, t_3))^\dagger = e^{i t_1 H_0} e^{-i(t_1-t_3)H} \mathbf{1} e^{i(t_2-t_3)H} e^{-i t_2 H_0}$$

$$U_I(t_1, t_3) (U_I(t_2, t_3))^\dagger = e^{i t_1 H_0} e^{-i(t_1-t_3)H} e^{i(t_2-t_3)H} e^{-i t_2 H_0}$$

$$U_I(t_1, t_3) (U_I(t_2, t_3))^\dagger = e^{i t_1 H_0} e^{-i(t_1-t_2)H} e^{-i t_2 H_0}$$

$$\boxed{U_I(t_1, t_3) U_I^\dagger(t_2, t_3) = U_I(t_1, t_2)}$$